

Sparse Phase Retrieval Algorithms for Frequency-Domain Optical Coherence Tomography

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1. Sparse phase retrieval in frequency-domain optical coherence tomography (FDOCT)

The goal in FDOCT is to reconstruct the backscattered wave $x(z)$, which encodes information about the specimen under consideration as a function of depth z , from Fourier magnitude measurement $I(\omega) = S(\omega) \left| 1 + \int_{-\infty}^{+\infty} x(z)e^{-j\omega z} dz \right|^2$ recorded by the spectrometer, where $S(\omega)$ is the source power spectrum. This is equivalent to retrieving the phase of the signal $\delta(z) + x(z)$, where $\delta(z)$ is the *Dirac delta function*, from the square of its Fourier magnitude spectrum. Since the reflected wave $x(z)$ exhibits strong peaks only at those locations where there is a significant change of refractive index in the specimen, the assumption of sparsity is apt in the context of FDOCT. In practice, one acquires samples of $I(\omega)$ and $S(\omega)$, since the measurements are acquired only at discrete wavelengths.

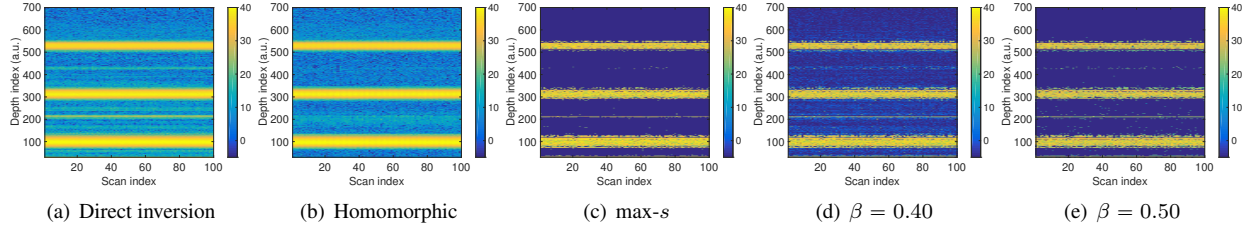


Figure 1: State-of-the-art techniques ((a) and (b)) vis-à-vis max-s (in (c)) and ℓ_0 -RAAR ((d) and (e)) for the glass specimen.

2. Proposed fixed-point algorithms and their performance

Let $\mathcal{S}_0 = \{\mathbf{u} \in \mathbb{R}^n : \mathbf{u} = \Psi\boldsymbol{\alpha}, \|\boldsymbol{\alpha}\|_0 \leq s\}$ be the set of all s -sparse signals in basis Ψ ; and $\mathcal{M} = \{\mathbf{u} \in \mathbb{R}^n : |\mathbf{F}\mathbf{u}| = \mathbf{y}\}$, where \mathbf{F} denotes the $n \times n$ discrete Fourier transform (DFT) matrix, be the set of all signals whose DFT magnitude matches with the measurement vector \mathbf{y} . In sparse PR, we seek to find a signal $\hat{\mathbf{x}}$ such that $\hat{\mathbf{x}} \in \mathcal{S}_0 \cap \mathcal{M}$. We recently proposed two iterative fixed-point algorithms [1], referred to as *max-s* and *relaxed averaged alternating reflections with ℓ_0 constraint* (ℓ_0 -RAAR), for solving this non-convex feasibility problem. Their update rules are given by $\mathbf{x}^{t+1} = \mathcal{P}_{\mathcal{S}_0}(\mathcal{P}_{\mathcal{M}}\mathbf{x}^t)$ and $\mathbf{x}^{t+1} = \mathcal{T}_\beta(\mathbf{x}^t)$, respectively, where \mathcal{T}_β is a combination of appropriately defined projection and reflection operators [2]. The max-s algorithm has the *error reduction property*, meaning that the measurement domain reconstruction error does not increase with iterations. The ℓ_0 -RAAR algorithm offers a generalized parameterized framework for FDOCT reconstruction, of which max-s and the direct inversion technique turn out to be special cases, corresponding to $\beta = \frac{1}{2}$ and $\beta = 0$, respectively. The performance of max-s and ℓ_0 -RAAR is validated on a specimen formed by stacking two microscopic glass slides. The sparsity is chosen as $s = 0.05n$, where $n = 2048$ samples are taken along each scan-line. The sparsifying basis Ψ is chosen to be the orthonormal *Haar* basis. We observe (cf. Fig. 1) that the proposed techniques yield tomograms without *autocorrelation artifacts* and superior signal-to-background noise ratio compared with the state-of-the-art.

References

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